## From Beth to van Benthem:

## Possibilities for Intuitionistic, <br> Classical, and Modal Logic

Workshop on the Future of Logic

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## On Semantics for Intuitionistic Logic

J. van Benthem. "The Information in Intuitionistic Logic," Synthese, 2009.
E. W. Beth. "Semantic Construction of Intuitionistic Logic," Mededelingen der Koninklijke Nederlandse Akademie van Wetenschappen, 1956.
D. van Dalen. "How to Glue Analysis Models," JSL, 1984.
A. Troesltra and D. van Dalen. Constructivism in Mathematics, 1988.

## On Possibility Semantics for Classical Logic

J. van Benthem. "Possible World Semantics for Classical Logic," Technical Report ZW-8018, Dept. of Mathematics, Rijksuniversiteit, Groningen, 1981.
J. van Benthem. "Partiality and Nonmonotonicity in Classical Logic," Logique et Analyse, 1986.
J. van Benthem. A Manual of Intensional Logic, Part III, 1988.

## On Possibility Semantics for Modal Logic

I. L. Humberstone. "From Worlds to Possibilities," JPL, 1981.
W. H. Holliday. "Partiality and Adjointness in Modal Logic," AiML, 2014, and several manuscripts in progress (email wesholliday@berkeley.edu for drafts).

## Two Paths to Possibility Semantics for Modal Logic

1. From Beth/Kripke Semantics for Intuitionistic Logic
1.1 Go Classical
1.2 Go Modal
2. From Relational Semantics for Modal Logic

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After sketching these two paths, l'll say something about

- The Program of Possibility Semantics.


## Information Models

We begin with information models $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ (cf. Frank Veltman's dissertation), i.e., Kripke models for intuitionistic PL:

- $S$ is a nonempty set;
- $\geqslant$ is a partial order on $S$;
- $\pi:$ At $\times S \rightarrow\{0,1\}$;
persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$.


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Although these authors think of the partial order $\geqslant$ as a branching temporal relation, arguably this specific idea is not essential.

What is essential is the more abstract idea that for partial information states $X$ and $X^{\prime}$, the relationship $X^{\prime} \geqslant X$ indicates that $X^{\prime}$ is a possible extension (refinement, enrichment, etc.) of $X$, so $X^{\prime}$ settles every issue that $X$ does and perhaps more.

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Not only intuitionistic logic, but also classical logic (Benthem 1981, Benthem 1986, Garson 2013) and various modal logics (Humberstone 1981, Veltman 1985, Holliday 2014, Yalcin 2014) can be given natural semantics using such structures.

## Kripke Forcing

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi$ as follows:

- $\mathcal{M}, \mathbf{X} \Vdash_{k} p$ iff $\pi(p, \mathbf{X})=1$;
- $\mathcal{M}, \mathbf{X} \Vdash_{k} \neg \varphi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \nVdash_{k} \varphi$;
- $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi \wedge \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi$ and $\mathcal{M}, \mathbf{X} \Vdash_{k} \psi$;
- $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi \vee \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi$ or $\mathcal{M}, \mathbf{X} \Vdash_{k} \psi$;
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Lemma (Persistence)
If $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\mathcal{M}, \mathbf{X}^{\prime} \Vdash_{k} \varphi$.

## Two Main Ideas

Go Classical:
Intuitionistic semantics should not have a monopoly on the use of partial information states. Classical semantics should also be able to use information models, albeit in a different way.

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Cf. Johan's (2009) "The Information in Intuitionistic Logic."

## Gödel Translation

Recall the Gödel translation:

- $p^{G}=\neg \neg p$;
- $(\neg \varphi)^{G}=\neg \varphi^{G}$;
- $(\varphi \wedge \psi)^{G}=\varphi^{G} \wedge \psi^{G}$;
- $(\varphi \vee \psi)^{G}=\neg\left(\neg \varphi^{G} \wedge \neg \psi^{G}\right)$;
- $(\varphi \rightarrow \psi)^{G}=\left(\varphi^{G} \rightarrow \psi^{G}\right)$.

Theorem (Gödel 1933)
For all $\varphi \in \mathcal{L}_{\mathrm{PL}}, \varphi$ is a theorem of classical propositional logic iff $\varphi^{G}$ is a theorem of intuitionistic propositional logic.

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Idea: let's implement the Gödel translation at the semantic level.

## Going Classical

First, recall:

- $\mathcal{M}, \mathbf{X} \Vdash_{k} \neg \neg p$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$.
$p^{G}=\neg \neg p$, so we will define:
- $\mathcal{M}, \mathbf{X} \Vdash_{c} p$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$.


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$(\neg \varphi)^{G}=\neg \varphi^{G},(\varphi \wedge \psi)^{G}=\varphi^{G} \wedge \psi^{G},(\varphi \rightarrow \psi)^{G}=\varphi^{G} \rightarrow \psi^{G}$, so the $\neg, \wedge$, and $\rightarrow$ clauses for $\Vdash_{c}$ will be the same as for $\Vdash_{k}$.

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Finally, observe:

- $\mathcal{M}, \mathbf{X} \Vdash_{k} \neg(\neg \varphi \wedge \neg \psi)$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}$ : $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{k} \varphi$ or $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{k} \psi$.
$(\varphi \vee \psi)^{G}=\neg\left(\neg \varphi^{G} \wedge \neg \psi^{G}\right)$, so we will define:
- $\mathcal{M}, \mathbf{X} \Vdash^{\circ} \varphi \vee \psi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}$ :
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## Classical Forcing

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \vdash_{c} \varphi$ as follows:

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Lemma (Persistence)
If $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\mathcal{M}, \mathbf{X}^{\prime} \Vdash_{c} \varphi$.

## Cofinality (Refinability)

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi$ as follows:

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- $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi \rightarrow \psi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}$ : if $\mathcal{M}, \mathbf{X}^{\prime} \Vdash_{c} \varphi$ then $\mathcal{M}, \mathbf{X}^{\prime} \Vdash^{c} \psi$.

Lemma (Cofinality)
If $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \varphi$, then $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi$.

## Refinability (Cofinality)

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Lemma (Refinability)
If $\mathcal{M}, \mathbf{X} \nVdash_{c} \varphi$, then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \Vdash_{c} \neg \varphi$.

## Classical Forcing

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi$ as follows:

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Theorem
Classical propositional logic is sound and complete with respect to the class of information models with the $\Vdash_{c}$ semantics.

## Kripke Forcing vs. Classical Forcing

So the differences are:

- $\mathcal{M}, \mathbf{X} \Vdash_{k} p$ iff $\pi(p, \mathbf{X})=1$;
- $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi \vee \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash_{k} \varphi$ or $\mathcal{M}, \mathbf{X} \Vdash_{k} \psi$;
vs.
- $\mathcal{M}, \mathbf{X} \Vdash_{c} p$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$;
- $\mathcal{M}, \mathbf{X} \Vdash_{c}(\varphi \vee \psi)$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}$ : $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \varphi$ or $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \psi$.


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"Classical logic is in less of a hurry than intuitionistic logic."

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As Johan (1981) remarks,
"Classical logic is in less of a hurry than intuitionistic logic."
We get a subtly different view of the contrast between classical and intuitionistic perspectives if we consider Beth semantics...

## Beth Forcing (à la van Dalen 1984)

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash_{b} \varphi$ as follows:

- $\mathcal{M}, \mathbf{X} \Vdash_{b} p$ iff $\forall$ paths $\mathcal{P}$ through $\mathbf{X} \exists \mathbf{X}^{\prime} \in \mathcal{P}: \pi\left(p, \mathbf{X}^{\prime}\right)=1$;
- $\mathcal{M}, \mathbf{X} \Vdash_{b} \neg \varphi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \nVdash_{b} \varphi$;
- $\mathcal{M}, \mathbf{X} \Vdash_{b} \varphi \wedge \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash_{b} \varphi$ and $\mathcal{M}, \mathbf{X} \Vdash_{b} \psi$;
- $\mathcal{M}, \mathbf{X} \Vdash_{b} \varphi \vee \psi$ iff $\forall$ paths $\mathcal{P}$ through $\mathbf{X} \exists \mathbf{X}^{\prime} \in \mathcal{P}$ : $\mathcal{M}, \mathbf{X}^{\prime} \Vdash_{b} \varphi$ or $\mathcal{M}, \mathbf{X}^{\prime} \Vdash_{b} \psi ;$
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## Beth Forcing vs. Classical Forcing

So the differences are:

- $\mathcal{M}, \mathbf{X} \Vdash_{b} p$ iff $\forall$ paths $\mathcal{P}$ through $\mathbf{X} \exists \mathbf{X}^{\prime} \in \mathcal{P}: \pi\left(p, \mathbf{X}^{\prime}\right)=1$;
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vs.
- $\mathcal{M}, \mathbf{X} \vdash_{c} p$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$;
- $\mathcal{M}, \mathbf{X} \vdash_{c} \varphi \vee \psi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}$ :
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\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \varphi \text { or } \mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \psi .
$$

The intuitionist wants it to be inevitable that one's information will include $p$ (or decide between $\varphi$ and $\psi$ ), whereas the classicist is satisfied if it is always possible to extend one's information to include $p$ (or decide between $\varphi$ and $\psi$ )-if $p$ (or the decision between $\varphi$ and $\psi$ ) is always available, rather than inevitable.

## Classical Forcing

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \vdash_{c} \varphi$ as follows:

- $\mathcal{M}, \mathbf{X} \Vdash_{c} p$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$;
- $\mathcal{M}, \mathbf{X} \Vdash_{c} \neg \varphi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \nVdash_{c} \varphi$;
- $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi \wedge \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash_{c} \varphi$ and $\mathcal{M}, \mathbf{X} \Vdash_{c} \psi$;
- $\mathcal{M}, \mathbf{X} \vdash^{\circ} \varphi \vee \psi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}:$ $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \varphi$ or $\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash_{c} \psi ;$
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## Classical Forcing

Given an information model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \vdash_{c} \varphi$ as follows:

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Final step toward propositional possibility semantics: let's push the $\forall \exists$ pattern even deeper, from $\Vdash$ to a condition on models.

## Propositional Possibility Models

Recall our information models $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ :

- $S$ is a nonempty set;
- $\geqslant$ is a partial order on $S$;
- $\pi:$ At $\times \wp(S) \rightarrow\{0,1\}$; persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$.


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A propositional possibility model is a model as above that satisfies: cofinality: if $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$, then $\pi(p, \mathbf{X})=1$.

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Johan's (1981) "Possible World Semantics for Classical Logic" studies possibility models for classical first-order logic.


## Propositional Possibility Models

Recall our information models $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ :

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A propositional possibility model is a model as above that satisfies:
refinability: if $\pi(p, \mathbf{X}) \uparrow$, then $\exists \mathbf{Y}, \mathbf{Z} \geqslant \mathbf{X}: \pi(p, \mathbf{Y})=0$,

$$
\pi(p, \mathbf{Z})=1
$$

Humberstone (1981) uses the stronger refinability condition.

## Propositional Possibility Models

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## Propositional Possibility Semantics

Given a propositional possibility model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash \varphi$ as follows:

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- $\mathcal{M}, \mathbf{X} \Vdash \neg \varphi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \nVdash \varphi$;
- $\mathcal{M}, \mathbf{X} \Vdash \varphi \wedge \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash \varphi$ and $\mathcal{M}, \mathbf{X} \Vdash \psi$;
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Lemma (Persistence)
If $\mathcal{M}, \mathbf{X} \Vdash \varphi$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\mathcal{M}, \mathbf{X}^{\prime} \Vdash \varphi$.

## Propositional Possibility Semantics

Given a propositional possibility model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{PL}}$, we define $\mathcal{M}, \mathbf{X} \Vdash \varphi$ as follows:

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Lemma (Cofinality)
If $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash \varphi$, then $\mathcal{M}, \mathbf{X} \Vdash \varphi$.

## Propositional Possibility Semantics

Given a propositional possibility model $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\text {PL }}$, we define $\mathcal{M}, \mathbf{X} \Vdash \varphi$ as follows:

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\mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash \varphi \text { or } \mathcal{M}, \mathbf{X}^{\prime \prime} \Vdash \psi ;
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- $\mathcal{M}, \mathbf{X} \Vdash \varphi \rightarrow \psi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}$ : if $\mathcal{M}, \mathbf{X}^{\prime} \Vdash \varphi$ then $\mathcal{M}, \mathbf{X}^{\prime} \Vdash \psi$.

Theorem
Classical propositional logic is sound and complete w.r.t. the class of propositional possibility models with the above semantics.

## Going Modal

Recall our information models $\mathcal{M}=\langle S, \geqslant, \pi\rangle$ :

- $S$ is a nonempty set;
- $\geqslant$ is a partial order on $S$;
- $\pi:$ At $\times \wp(S) \rightarrow\{0,1\}$;
persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$.
A propositional possibility model is a model as above that satisfies: cofinality: if $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$, then $\pi(p, \mathbf{X})=1$.

Q: what kind of structure should we add to these for modal logic?

The philosophical man in the street occasionally speaks of so-and-so's 'belief-world': the world as so-and-so believes it to be. And philosophers rightly protest at such terminology since .... a person may believe a disjunction without believing either disjunct, so that there really is no such thing as the world as so-and-so believes it to be. Rather, in such cases as the ones just envisaged, what we have is that the disjunction holds at every one of so-and-so's belief compatible worlds, the one disjunct holding at some, the other at others ....

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The philosophers' objection to the 'belief-world' locution is well taken, and it may be respected while at the same time justice is done to the man in the street's idea that (not quite putting it in his own terms) there should be a single entity such that truth with respect to it coincides with being believed by so-and-so; the entity won't be a possible world, but, instead, a possibility. (Humberstone 1981, 334)

## Functional Possibility Models

In my AiML 2014 paper, I introduced the following modification of Humberstone's (1981) original modal possibility models.

A functional possibility model is a tuple $\mathcal{M}=\left\langle S, \geqslant,\left\{f_{a}\right\}_{a \in I}, \pi\right\rangle$ :

- $S$ is a set with a distinguished element $\perp_{\mathcal{M}} ; \boldsymbol{S}=S-\left\{\perp_{\mathcal{M}}\right\}$;
$\bullet \geqslant$ is a partial order on $\boldsymbol{S} ; \mathbf{X} \mathbb{V} \mathbf{Y}$ iff $\exists \mathbf{Z} \in \mathbf{S}: \mathbf{Z} \geqslant \mathbf{X}$ and $\mathbf{Z} \geqslant \mathbf{Y}$;


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- $\geqslant$ is a partial order on $\boldsymbol{S}$;
- $f_{a}: \boldsymbol{S} \rightarrow \boldsymbol{S}$ (for $\mathbf{X} \in \boldsymbol{S}, f_{a}(\mathbf{X})$ is agent a's belief-possibility at $\mathbf{X}$ );


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- $f_{a}: S \rightarrow \boldsymbol{S}$;
- $\pi:$ At $\times \boldsymbol{S} \rightarrow\{0,1\}$;
persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$;
cofinality: if $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$, then $\pi(p, \mathbf{X})=1$;


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modal analogue of persistence...
modal analogue of cofinality...


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- $f_{a}: S \rightarrow \boldsymbol{S}$;
- $\pi:$ At $\times \boldsymbol{S} \rightarrow\{0,1\}$; persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$; cofinality: if $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$, then $\pi(p, \mathbf{X})=1$; $f$-persistence: if $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $f_{a}\left(\mathbf{X}^{\prime}\right) \geqslant f_{a}(\mathbf{X})$; modal analogue of cofinality...


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persistence: if $\pi(p, \mathbf{X}) \downarrow$ and $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $\pi\left(p, \mathbf{X}^{\prime}\right)=\pi(p, \mathbf{X})$;
cofinality: if $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X} \exists \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime} \pi\left(p, \mathbf{X}^{\prime \prime}\right)=1$, then $\pi(p, \mathbf{X})=1$;
$f$-persistence: if $\mathbf{X}^{\prime} \geqslant \mathbf{X}$, then $f_{a}\left(\mathbf{X}^{\prime}\right) \geqslant f_{a}(\mathbf{X})$;
$f$-refinability: if $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$, then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X} \forall \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \mathbf{Y} \boxtimes f_{a}\left(\mathbf{X}^{\prime \prime}\right)$.


## Functional Possibility Semantics

Given a functional possibility model $\mathcal{M}=\left\langle S, \geqslant,\left\{f_{a}\right\}_{a \in I}, \pi\right\rangle$ with $\mathbf{X} \in S$ and $\varphi \in \mathcal{L}_{\mathrm{ML}}$, we define $\mathcal{M}, \mathbf{X} \Vdash \varphi$ as follows:

- $\mathcal{M}, \perp_{\mathcal{M}} \Vdash \varphi$ for all $\varphi \in \mathcal{L}_{\mathrm{ML}}$;
- $\mathcal{M}, \mathbf{X} \Vdash p$ iff $\pi(p, \mathbf{X})=1$;
- $\mathcal{M}, \mathbf{X} \Vdash \neg \varphi$ iff $\forall \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{X}^{\prime} \nVdash \varphi$;
- $\mathcal{M}, \mathbf{X} \Vdash \varphi \wedge \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash \varphi$ and $\mathcal{M}, \mathbf{X} \Vdash \psi$;
- $\mathcal{M}, \mathbf{X} \Vdash \square_{a} \varphi$ iff $\mathcal{M}, f_{a}(\mathbf{X}) \Vdash \varphi$.

Humberstone (1981): "there should be a single entity such that truth with respect to it coincides with being believed by so-and-so."

As usual, we can define $\varphi \vee \psi:=\neg(\neg \varphi \wedge \neg \psi)$,
$\varphi \rightarrow \psi:=\neg(\varphi \wedge \neg \psi), \diamond_{a} \varphi:=\neg \square_{a} \neg \varphi$.

Definition (Possibilization)
Given a relational world model $\mathfrak{M}=\left\langle W,\left\{R_{a}\right\}_{a \in I}, V\right\rangle$, define the powerset possibilization of $\mathfrak{M}, \mathfrak{M}^{\star}=\left\langle S, \geqslant,\left\{f_{a}\right\}_{a \in I}, \pi\right\rangle$ :

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Given a relational world model $\mathfrak{M}=\left\langle W,\left\{R_{a}\right\}_{a \in I}, V\right\rangle$, define the powerset possibilization of $\mathfrak{M}, \mathfrak{M}^{\star}=\left\langle S, \geqslant,\left\{f_{a}\right\}_{a \in I}, \pi\right\rangle$ :

$$
\text { 1. } S=\wp(W) \text { and } \perp_{\mathfrak{M}^{\star}}=\varnothing ; \quad \text { 2. } X \geqslant Y \text { iff } X \subseteq Y ;
$$

$$
\text { 3. } f_{\mathrm{a}}(X)=R_{\mathrm{a}}[X]=\left\{y \in W \mid \exists x \in X: x R_{\mathrm{a}} y\right\} \text {; }
$$

$$
\text { 4. } \pi(p, X)= \begin{cases}1 & \text { if } \forall x \in X: V(p, x)=1 \\ 0 & \text { if } \forall x \in X: V(p, x)=0 \text { and } X \neq \varnothing \\ \text { undef. } & \text { otherwise }\end{cases}
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## Definition (Possibilization)

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\end{aligned}
$$

## Lemma (From Worlds to Possibilities)

For any relational world model $\mathfrak{M}=\left\langle W,\left\{R_{a}\right\}_{a \in I}, V\right\rangle$ :

1. $\mathfrak{M}^{\star}$ is a functional possibility model;
2. $\mathfrak{M}^{\star}, X \Vdash \varphi$ iff for all $x \in X, \mathfrak{M}, x \vDash \varphi$.

## Axiomatization

Axioms: as usual, $D$ is $\square_{a} \varphi \rightarrow \neg \square_{a} \neg \varphi$, $T$ is $\square_{a} \varphi \rightarrow \varphi, 4$ is $\square_{a} \varphi \rightarrow \square_{a} \square_{a} \varphi$, B is $\neg \varphi \rightarrow \square_{a} \neg \square_{a} \varphi$, and 5 is $\neg \square{ }_{a} \varphi \rightarrow \square_{a} \neg \square_{a} \varphi$.

Theorem (Soundness and Strong Completeness)
For any subset of $\{D, T, 4, B, 5\}$, the extension of the modal logic $\mathbf{K}$ (in its polymodal version) with that set of axioms is sound and strongly complete with respect to the class of functional possibility models satisfying the associated condition for each axiom:

D axiom: for all $\mathbf{X}, f_{a}(\mathbf{X}) \neq \perp$;
T axiom: for all $\mathbf{X}, \mathbf{X} \geqslant f_{a}(\mathbf{X})$;
4 axiom: for all $\mathbf{X}, f_{a}\left(f_{a}(\mathbf{X})\right) \geqslant f_{a}(\mathbf{X})$;
B axiom: for all $\mathbf{X}, \mathbf{Y}$, if $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$ then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X}: \mathbf{X}^{\prime} \geqslant f_{a}(\mathbf{Y})$;
5 axiom: for all $\mathbf{X}, \mathbf{Y}$, if $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$, then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X}: f_{a}\left(\mathbf{X}^{\prime}\right) \geqslant f_{a}(\mathbf{Y})$.

## A Simpler Completeness Proof

The infinitary baggage that comes with possible worlds-maximally consistent sets and Lindenbaum's Lemma-are not involved in the completeness proof, which takes the domain of the canonical model to simply be the set of sets of formulas (modulo equivalence).

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(Incidentally, as a result, the proof easily generalizes to uncountable languages without the use of the Axiom of Choice.)

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(Incidentally, as a result, the proof easily generalizes to uncountable languages without the use of the Axiom of Choice.)

In fact, to prove the weak completeness of many standard extensions of $\mathbf{K}$, we can take the domain of the canonical model to simply be the set of individual formulas (modulo equivalence).

## The Problem of the Irrelevant Extension

Van Benthem (1988, p. 78): "There is something inelegant to an ordinary Henkin argument. One has a consistent set of sentences $S$, perhaps quite small, that one would like to see satisfied semantically. Now, some arbitrary maximal extensions $S^{+}$of $S$ is to be taken to obtain a model (for $S^{+}$, and hence for $S$ )-but the added part $S^{+}-S$ plays no role subsequently. We started out with something partial, but the method forces us to be total."

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This "problem of the "irrelevant extension'" (van Benthem 1981, p. $1)$ is solved by possibility semantics for classical and modal logic.

> Possibilities differ from possible worlds in leaving many details unspecified.... I am counting the possibility that the die land six-up as one possibility. There are indefinitely many possible worlds compatible with this one possibility-which vary not only in the precise location and orientation of the landed die, but also as to whether it is raining in China at the time, or at any other time, and so on ad infinitum....

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## Banning Worlds

Humberstone and other philosophers discuss the idea that possibilities (unlike total worlds) can always be further refined:

- $\mathcal{M}$ is infinitely ascending iff $\forall \mathbf{X} \in \boldsymbol{S} \exists \mathbf{X}^{\prime} \in \boldsymbol{S}: \mathbf{X}^{\prime}>\mathbf{X}$.

I also consider the condition that each possibility settles only finitely many atomic facts (we are assuming At is infinite):

- $\mathcal{M}$ is locally finite iff $\forall \mathbf{X} \in \boldsymbol{S}:\{p \in \operatorname{At} \mid \pi(p, \mathbf{X}) \downarrow\}$ is finite.

For completeness w.r.t to locally finite models, the proof depends more on the particular logic, so we treat epistemic/doxastic logics:

Theorem (Completeness Cont.)
Each $\mathbf{L} \in\{\mathbf{K}, \mathbf{K D}, \mathbf{T}, \mathbf{K} 4, \mathrm{KD} 4, \mathbf{K 4 5}, \mathrm{KD} 45, \mathbf{S 4}, \mathbf{S} 5\}$ is complete w.r.t the class of locally finite and infinitely ascending possibility models with the conditions associated with L's axioms:

D axiom: for all $\mathbf{X}, f_{a}(\mathbf{X}) \neq \perp$;
T axiom: for all $\mathbf{X}, \mathbf{X} \geqslant f_{a}(\mathbf{X})$;
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This is proved by constructing a canonical possibility model whose points are (equivalence classes of) individual finite formulas.

## Two Parts of the Program

1. show how familiar modal languages can be given possibility semantics instead of world semantics, revealing
1.1 which of the assumptions about the nature and structure of possibilities that are built into world models are (un)necessary to obtain familiar logics for these languages and
1.2 which alternative assumptions about possibilities, assumptions that are inconsistent with those built into world models, are compatible with familiar logics for these languages;

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1.2 which alternative assumptions about possibilities, assumptions that are inconsistent with those built into world models, are compatible with familiar logics for these languages;
2. identify extended languages for which possibility semantics allows us to obtain new logics that we cannot obtain with standard world semantics, or with possibilities as sets of worlds, revealing the limitations of world-based modeling.

## Extended Languages

For an example of the point about expanded languages, suppose that we add to our language the Kripke and Beth disjunctions:

- $\mathcal{M}, \mathbf{X} \Vdash \varphi \vee_{k} \psi$ iff $\mathcal{M}, \mathbf{X} \Vdash \varphi$ or $\mathcal{M}, \mathbf{X} \Vdash \psi$;
- $\mathcal{M}, \mathbf{X} \Vdash \varphi \vee_{b} \psi$ iff for $\forall$ paths $\mathcal{P}$ through $\mathbf{X} \exists \mathbf{X}^{\prime} \in \mathcal{P}$ :
$\mathcal{M}, \mathbf{X}^{\prime} \Vdash \varphi$ or $\mathcal{M}, \mathbf{X}^{\prime} \Vdash \psi$.


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Then as Ivano Ciardelli observed, the Kreisel-Putnam principle

$$
\left(\alpha \rightarrow_{k}\left(\varphi \vee_{k} \psi\right)\right) \rightarrow_{k}\left(\left(\alpha \rightarrow_{k} \varphi\right) \vee_{k}\left(\alpha \rightarrow_{k} \psi\right)\right)
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for $\alpha$ not containing $\vee_{k}$, is valid over possibilizations of world models. But it is not valid over all possibility models.

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And the principle $\varphi \vee_{b} \neg \varphi$ is valid over possibilizations of world models. But it is not valid over all possibility models.

## Further Directions

- Possibility models for first-order ML (Harrison-Trainor 2014)
- Possibility models for epistemic modals (Yalcin 2014)
- Possibility models for dynamic epistemic logic (Holliday 2014)
- Possibility models for (un)awareness in epistemic logic
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- and more...


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## Stay tuned or join the project!

## Thank You

## \&

## Thanks to Johan

for inspiring so many of us!

## Appendix

Refinability: if $\mathcal{M}, \mathbf{X} \nVdash \varphi$, then $\exists \mathbf{Y} \geqslant \mathbf{X}: \mathcal{M}, \mathbf{Y} \Vdash \neg \varphi$.

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Assume $\mathcal{M}, \mathbf{X} \nVdash \square_{a} \varphi$, so $\mathcal{M}, f_{a}(\mathbf{X}) \nVdash \varphi$ by the truth def. Then by the inductive hypothesis there is a $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$ with $\mathcal{M}, \mathbf{Y} \Vdash \neg \varphi$.

## Appendix

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$$
\mathbf{X}+--\cdots-\cdots f_{a}(\mathbf{X}) \nVdash \varphi, \mathbf{Y} \Vdash \neg \varphi
$$

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Now we need an $\mathbf{X}^{\prime} \geqslant \mathbf{X}$ with $\mathcal{M}, \mathbf{X}^{\prime} \Vdash \neg \square{ }_{a} \varphi$

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$$
\begin{aligned}
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& \forall \uparrow
\end{aligned}
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Now suppose we had a $\mathbf{X}^{\prime} \geqslant \mathbf{X}$ such that for all $\mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}$, $f_{a}\left(\mathbf{X}^{\prime \prime}\right) \bigvee \mathbf{Y}$. Then since $\mathcal{M}, \mathbf{Y} \Vdash \neg \varphi$, we'd have $\mathcal{M}, f_{a}\left(\mathbf{X}^{\prime \prime}\right) \nVdash \varphi$ by Persistence.

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$f$-refinability: if $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$, then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X} \forall \mathbf{X}^{\prime \prime} \geqslant \mathbf{X}^{\prime}: \mathbf{Y} \mathbb{V} f_{a}\left(\mathbf{X}^{\prime \prime}\right)$.

## Appendix

T axiom $-\square_{a} \varphi \rightarrow \varphi$

## T axiom: for all $\mathbf{X}, \mathbf{X} \geqslant f_{a}(\mathbf{X})$.

## 4 axiom - $\square_{a} \varphi \rightarrow \square_{a} \square_{a} \varphi$

4 axiom: for all $\mathbf{X}, f_{a}\left(f_{a}(\mathbf{X})\right) \geqslant f_{a}(\mathbf{X})$.


B axiom $-\neg \varphi \rightarrow \square_{a} \neg \square_{a} \varphi$

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## 5 axiom - $\neg \square_{a} \varphi \rightarrow \square_{a} \neg \square_{a} \varphi$

5 axiom: for all $\mathbf{X}, \mathbf{Y}$, if $\mathbf{Y} \geqslant f_{a}(\mathbf{X})$, then $\exists \mathbf{X}^{\prime} \geqslant \mathbf{X}: f_{a}\left(\mathbf{X}^{\prime}\right) \geqslant f_{a}(\mathbf{Y})$.


