

# A complete axiomatization of Euclidean strong non-contingency logic

Philippe Balbiani<sup>1</sup> and Jie Fan<sup>2</sup>

<sup>1</sup>Institut de recherche en informatique de Toulouse CNRS — Toulouse University, France

<sup>2</sup>School of Philosophy, Beijing Normal University, China

**Abstract.** This article provides a complete axiomatization for strong non-contingency logic over Euclidean frames, whose completeness proof is nontrivial. Our result answers an open question raised in [3].

## 1 Introduction

Past decades have witnessed a variety of research on logics with a sole primitive modality that is essentially a combination of another modality and boolean connectives. For instance, in non-contingency logic [10,1,7,8,2,4,5], a formula is noncontingent iff it is either necessarily true or necessarily false, whereas a formula is contingent iff it is possibly true and also possibly false, in symbol,  $\Delta\varphi = \Box\varphi \vee \Box\neg\varphi$ ,  $\nabla\varphi = \Diamond\varphi \wedge \Diamond\neg\varphi$ ; in the logic of essence and accident [9,11], a formula is essential iff once it is true, it is necessarily true, while a formula is accident iff it is true but possibly false, in symbol,  $\circ\varphi = \varphi \rightarrow \Box\varphi$ ,  $\bullet\varphi = \varphi \wedge \Diamond\neg\varphi$ ; in the logic for false belief [12],  $\varphi$  is a false belief iff  $\varphi$  is false but believed, in symbol,  $W\varphi = \neg\varphi \wedge B\varphi$ . Despite being definable with known modalities such as necessity/belief, these modalities have philosophical interests in their own right, and deserve to be studied independently.

Recently, Fan [3] has introduced the notion of *strong non-contingency* by saying that a formula is strongly non-contingent iff it is necessarily true when it is true and it is necessarily false when it is false. This notion is related to Hintikka's treatment of question embedding verbs like 'know', 'remember' in [6]. According to his treatment, "Mary knows (remembers) whether it is raining" is equivalent to "if it is raining, then Mary knows (remembers) it is raining, and if it is not raining, then Mary knows (remembers) it is not raining". Just as necessity means (propositional) knowledge in the setting of epistemic logic, strong non-contingency means knowledge whether in the sense of Hintikka's aforementioned treatment.

As shown in [3], the logic with strong non-contingency as a sole primitive modality, a non-normal modal logic, is less expressive than standard modal logic on various classes of models, and cannot define many usual frame properties including Euclideanity. This may invite technical difficulties and novelties in completely axiomatizing this new logic over various frames. [3] has completely axiomatized different modal logics of strong non-contingency, and leave open the question of the complete axiomatization of the modal logic of strong non-contingency determined by the class of all Euclidean frames. In this note, we answer the open question.

## 2 Formal definitions

We adopt the notation from [3].

*Syntax* Let  $ATO$  be a countable set of atoms ( $p, q$ , etc). The set  $FOR$  of all formulas ( $\varphi, \psi$ , etc) is inductively defined as follows:

$$- \varphi ::= p \mid \perp \mid \neg\varphi \mid (\varphi \vee \psi) \mid \blacktriangle\varphi.$$

The formula  $\blacktriangledown\varphi$  is obtained as an abbreviation for  $\blacktriangledown\varphi ::= \neg\blacktriangle\varphi$ . The formulas  $\varphi^0, \varphi^1$  and  $\varphi^2$  are respectively obtained as abbreviations for  $\blacktriangledown\varphi \wedge \blacktriangle\blacktriangle\varphi, \varphi \wedge \blacktriangle\varphi$  and  $\neg\varphi \wedge \blacktriangle\varphi$ .

*Semantics* A frame is a structure of the form  $\mathcal{F} = (W, R)$  where  $W$  is a nonempty set of states ( $s, t$ , etc) and  $R$  is a binary relation on  $W$ . A model based on a frame  $\mathcal{F} = (W, R)$  is a structure of the form  $\mathcal{M} = (W, R, V)$  where  $V$  is a valuation on  $W$ , i.e. a function associating to each atom  $p$  a set  $V(p)$  of states. Atoms and Boolean connectives being classically interpreted, we inductively define the truth of  $\varphi \in FOR$  in model  $\mathcal{M} = (W, R, V)$  at state  $s \in W$  ( $\mathcal{M}, s \models \varphi$ ) as follows:

$$- \mathcal{M}, s \models \blacktriangle\varphi \text{ iff if } \mathcal{M}, s \models \varphi \text{ then } \mathcal{M}, t \models \varphi \text{ for all states } t \in W \text{ such that } sRt \text{ and } \text{if } \mathcal{M}, s \not\models \varphi \text{ then } \mathcal{M}, t \not\models \varphi \text{ for all states } t \in W \text{ such that } sRt.$$

Let  $\mathcal{F} = (W, R)$  be a frame. We shall say  $\varphi \in FOR$  is  $\mathcal{F}$ -valid ( $\mathcal{F} \models \varphi$ ) iff for all models  $\mathcal{M}$  based on  $\mathcal{F}$  and for all states  $s \in W, \mathcal{M}, s \models \varphi$ . Let  $\mathcal{C}$  be a class of frames. We shall say  $\varphi \in FOR$  is  $\mathcal{C}$ -valid ( $\mathcal{C} \models \varphi$ ) iff for all frames  $\mathcal{F}$  in  $\mathcal{C}, \mathcal{F} \models \varphi$ . The logic determined by a class  $\mathcal{C}$  of frames ( $Log(\mathcal{C})$ ) is the set of  $\varphi \in FOR$  such that  $\mathcal{C} \models \varphi$ .

*Generated subframes* The subframe of a frame  $\mathcal{F} = (W, R)$  generated by a state  $s \in W$  is the restriction of  $\mathcal{F}$  to the states in  $R^*(s)$  where  $R^*$  is the reflexive transitive closure of  $R$ ; in other words,  $R^* = \bigcup_{n \in \mathbb{N}} R^n$ . We shall say that a frame  $\mathcal{F} = (W, R)$  is generated iff there exists a state  $s \in W$  such that  $R^*(s) = W$ .

**Proposition 1 (Generated Subframe Lemma).** *Let  $\mathcal{F} = (W, R)$  and  $\mathcal{F}' = (W', R')$  be frames. If  $\mathcal{F}'$  is a subframe of  $\mathcal{F}$  generated by a state  $s \in W$  then for all  $\varphi \in FOR$ , if  $\mathcal{F} \models \varphi$  then  $\mathcal{F}' \models \varphi$ .*

*Bounded morphisms* Let  $\mathcal{F} = (W, R)$  and  $\mathcal{F}' = (W', R')$  be frames. A function  $\mu$  associating to each state  $s \in W$  a state  $\mu(s) \in W'$  is said to be a bounded morphism from  $\mathcal{F}$  to  $\mathcal{F}'$  iff the following conditions hold:

$$\begin{aligned} - & \text{ If } sRt \text{ and } s \neq t \text{ then } \mu(s)R'\mu(t). \\ - & \text{ If } \mu(s)R't' \text{ and } \mu(s) \neq t' \text{ then there exists a state } t \in W \text{ such that } sRt \text{ and } \mu(t) = t'. \end{aligned}$$

We shall say that  $\mathcal{F}'$  is a bounded morphic image of  $\mathcal{F}$  iff there exists a surjective bounded morphism from  $\mathcal{F}$  to  $\mathcal{F}'$ .

**Proposition 2 (Bounded Morphism Lemma).** *Let  $\mathcal{F} = (W, R)$  and  $\mathcal{F}' = (W', R')$  be frames. If  $\mathcal{F}'$  is a bounded morphic image of  $\mathcal{F}$  then for all  $\varphi \in FOR$ , if  $\mathcal{F} \models \varphi$  then  $\mathcal{F}' \models \varphi$ .*

*Euclidean frames* A frame  $\mathcal{F} = (W, R)$  is said to be Euclidean iff for all states  $s, t, u \in W$ , if  $sRt$  and  $sRu$  then  $tRu$  and  $uRt$ . Let  $\mathcal{C}_{euc}$  be the class of all Euclidean frames.

**Proposition 3.** *Let  $\mathcal{F} = (W, R)$  be an Euclidean frame. For all states  $s \in W$ ,  $R^*(s) = \{s\} \cup R(s) \cup R(R(s))$ .*

*Proof.* By the definition of  $R^*$ , we need only show

$$(*) \quad \text{for all } n \geq 3, R^n(s) \subseteq R(R(s)).$$

We prove this by induction on  $n \geq 3$ .

- $n = 3$ . Suppose  $t \in R^3(s)$ , then there exist  $u_1, u_2$  such that  $sRu_1Ru_2Rt$ . Since  $R$  is Euclidean,  $u_1Ru_1$ , and then  $u_2Ru_1$ . From this and  $u_2Rt$ , by using Euclideanity of  $R$ , we obtain  $u_1Rt$ , then  $t \in R(R(s))$ .
- Inductively hypothesize (IH) that  $(*)$  holds for  $n = k$ , we show it also holds for  $n = k+1$ . Assume  $t \in R^{k+1}(s)$ , then there is a  $u$  such that  $sR^k uRt$ . By  $u \in R^k(s)$  and IH, we derive  $u \in R(R(s))$ , and thus  $t \in R^3(s)$ . By a similar argument as the case  $n = 3$ , we conclude that  $t \in R(R(s))$ .

Let  $A, B$  and  $C$  be pairwise disjoint sets. Let  $\mathcal{F}_{B,C}^A = (W_{B,C}^A, R_{B,C}^A)$  be the frame such that  $W_{B,C}^A = A \cup B \cup C$  and  $R_{B,C}^A = \{(s, t) : \text{either } s \notin A \text{ and } t \in C, \text{ or } t \in B\}$ .

**Proposition 4.** *Let  $A, B$  and  $C$  be pairwise disjoint sets. Then  $\mathcal{F}_{B,C}^A$  is in  $\mathcal{C}_{euc}$ .*

*Proof.* Suppose  $\mathcal{F}_{B,C}^A$  is not in  $\mathcal{C}_{euc}$ . Let  $s, t, u \in W_{B,C}^A$  be states such that  $sR_{B,C}^A t, sR_{B,C}^A u$  and either not  $tR_{B,C}^A u$ , or not  $uR_{B,C}^A t$ . Without loss of generality, suppose not  $tR_{B,C}^A u$ . Since  $sR_{B,C}^A t$ , therefore either  $s \notin A$  and  $t \in C$ , or  $t \in B$ . Hence, either  $t \in C$ , or  $t \in B$ . Since  $sR_{B,C}^A u$ , therefore either  $s \notin A$  and  $u \in C$ , or  $u \in B$ . Thus, either  $u \in C$ , or  $u \in B$ . Since not  $tR_{B,C}^A u$ , therefore either  $t \in A$ , or  $u \notin C$ . Moreover,  $u \notin B$ . Since either  $t \in C$ , or  $t \in B$ , therefore  $u \notin C$ : a contradiction.

**Proposition 5.** *Let  $\mathcal{F} = (W, R)$  be a generated Euclidean frame. There exists pairwise disjoint sets  $A, B$  and  $C$  such that  $\mathcal{F}$  is a bounded morphic image of  $\mathcal{F}_{B,C}^A$ .*

*Proof.* Let  $s \in W$  be a state such that  $R^*(s) = W$ . Since  $\mathcal{F}$  is Euclidean, therefore  $W = \{s\} \cup R(s) \cup R(R(s))$ . Let  $A, B$  and  $C$  be the pairwise disjoint sets defined as follows:

- $A = \{(s, 0)\}$ .
- $B = \{(t, 1) : t \in R(s)\}$ .
- $C = \{(u, 2) : u \in R(R(s))\}$ .

Let  $\mu$  be the function associating to each state  $x \in W_{B,C}^A$  a state  $\mu(x) \in W$  defined as follows:

- $\mu(s, 0) = s$ .
- For all  $t \in R(s)$ ,  $\mu(t, 1) = t$ .
- For all  $u \in R(R(s))$ ,  $\mu(u, 2) = u$ .

Obviously,  $\mu$  is a surjective bounded morphism from  $\mathcal{F}_{B,C}^A$  to  $\mathcal{F}$ .

### 3 Axiomatization

Let  $L_{\text{euc}}^{\blacktriangle}$  be the least set of formulas closed under the inference rules of modus ponens and uniform substitution, closed under the inference rule  $\frac{\varphi \rightarrow \psi}{\varphi \wedge \blacktriangle\varphi \rightarrow \psi \wedge \blacktriangle\psi}$ , containing all propositional tautologies and containing the following formulas:

- (K1)  $\blacktriangle\top$ ,
- (K2)  $\blacktriangle\neg p \leftrightarrow \blacktriangle p$ ,
- (K3)  $\blacktriangle p \wedge \blacktriangle q \rightarrow \blacktriangle(p \wedge q)$ ,
- (A1)  $\blacktriangledown(p \wedge q^1) \wedge \blacktriangledown(p \wedge \neg q^1) \rightarrow p$ ,
- (A2)  $\blacktriangle(p \wedge q^0) \wedge \blacktriangle(p \wedge q^1) \wedge \blacktriangle(p \wedge q^2) \rightarrow p \vee \blacktriangle p$ .

The inference rule  $\frac{\varphi \rightarrow \psi}{\varphi \wedge \blacktriangle\varphi \rightarrow \psi \wedge \blacktriangle\psi}$  and the formulas (K1), (K2) and (K3) have already been considered in [3].

**Proposition 6 (Soundness).** *For all  $\varphi \in \text{FOR}$ , if  $\varphi \in L_{\text{euc}}^{\blacktriangle}$  then  $\varphi \in \text{Log}(\mathcal{C}_{\text{euc}})$ .*

*Proof.* Suppose (A1) is not in  $\text{Log}(\mathcal{C}_{\text{euc}})$ . Let  $\mathcal{F} = (W, R)$  be an Euclidean frame,  $\mathcal{M} = (W, R, V)$  be a model based on  $\mathcal{F}$  and  $s \in W$  be a state such that  $\mathcal{M}, s \not\models \blacktriangledown(p \wedge q^1) \wedge \blacktriangledown(p \wedge \neg q^1) \rightarrow p$ . Hence,  $\mathcal{M}, s \models \blacktriangledown(p \wedge q^1)$ ,  $\mathcal{M}, s \models \blacktriangledown(p \wedge \neg q^1)$  and  $\mathcal{M}, s \not\models p$ . Let  $t, u \in W$  be states such that  $sRt$ ,  $sRu$ ,  $\mathcal{M}, t \models q^1$  and  $\mathcal{M}, u \not\models q^1$ . Thus,  $\mathcal{M}, t \models q$ ,  $\mathcal{M}, t \models \blacktriangle q$  and either  $\mathcal{M}, u \not\models q$ , or  $\mathcal{M}, u \not\models \blacktriangle q$ . Since  $\mathcal{F}$  is Euclidean,  $sRt$  and  $sRu$ , therefore  $tRu$ . Since  $\mathcal{M}, t \models q$  and  $\mathcal{M}, t \models \blacktriangle q$ , therefore  $\mathcal{M}, u \models q$ . Since either  $\mathcal{M}, u \not\models q$ , or  $\mathcal{M}, u \not\models \blacktriangle q$ , therefore  $\mathcal{M}, u \not\models \blacktriangle q$ . Since  $\mathcal{M}, u \models q$ , therefore let  $v \in W$  be a state such that  $uRv$  and  $\mathcal{M}, v \not\models q$ . Since  $\mathcal{F}$  is Euclidean,  $sRt$ ,  $sRu$  and  $uRv$ , therefore  $tRv$ . Since  $\mathcal{M}, t \models q$  and  $\mathcal{M}, t \models \blacktriangle q$ , therefore  $\mathcal{M}, v \models q$ : a contradiction.

Suppose (A2) is not in  $\text{Log}(\mathcal{C}_{\text{euc}})$ . Let  $\mathcal{F} = (W, R)$  be an Euclidean frame,  $\mathcal{M} = (W, R, V)$  be a model based on  $\mathcal{F}$  and  $s \in W$  be a state such that  $\mathcal{M}, s \not\models \blacktriangle(p \wedge q^0) \wedge \blacktriangle(p \wedge q^1) \wedge \blacktriangle(p \wedge q^2) \rightarrow p \vee \blacktriangle p$ . Hence,  $\mathcal{M}, s \models \blacktriangle(p \wedge q^0)$ ,  $\mathcal{M}, s \models \blacktriangle(p \wedge q^1)$ ,  $\mathcal{M}, s \models \blacktriangle(p \wedge q^2)$ ,  $\mathcal{M}, s \not\models p$  and  $\mathcal{M}, s \not\models \blacktriangle p$ . Let  $t \in W$  be a state such that  $sRt$  and  $\mathcal{M}, t \models p$ . Since  $\mathcal{M}, s \models \blacktriangle(p \wedge q^0)$ ,  $\mathcal{M}, s \models \blacktriangle(p \wedge q^1)$ ,  $\mathcal{M}, s \models \blacktriangle(p \wedge q^2)$  and  $\mathcal{M}, s \not\models p$ , therefore  $\mathcal{M}, t \not\models p \wedge q^0$ ,  $\mathcal{M}, t \not\models p \wedge q^1$  and  $\mathcal{M}, t \not\models p \wedge q^2$ . Since  $\mathcal{M}, t \models p$ , therefore  $\mathcal{M}, t \not\models q^0$ ,  $\mathcal{M}, t \not\models q^1$  and  $\mathcal{M}, t \not\models q^2$ . Thus,  $\mathcal{M}, t \not\models \blacktriangle q$  and  $\mathcal{M}, t \not\models \blacktriangle\blacktriangle q$ . Without loss of generality, suppose  $\mathcal{M}, t \models q$ . Let  $u, v \in W$  be a state such that  $tRu$ ,  $tRv$ ,  $\mathcal{M}, u \not\models q$  and  $\mathcal{M}, v \models \blacktriangle q$ . Since  $\mathcal{F}$  is Euclidean,  $sRt$ ,  $tRu$  and  $tRv$ , therefore  $vRt$  and  $vRu$ . Since  $\mathcal{M}, v \models \blacktriangle q$  and  $\mathcal{M}, t \models q$ , therefore  $\mathcal{M}, v \models q$ . Since  $\mathcal{M}, v \models \blacktriangle q$ ,  $\mathcal{M}, u \not\models q$  and  $vRu$ , therefore  $\mathcal{M}, v \not\models q$ : a contradiction.

We end this section by giving examples of derivable formulas. Let us consider the following formulas:

- (A3)  $\blacktriangledown(p \wedge q^0) \wedge \blacktriangledown(p \wedge \neg q^0) \rightarrow p$ ,
- (A4)  $\blacktriangledown(p \wedge q^2) \wedge \blacktriangledown(p \wedge \neg q^2) \rightarrow p$ ,
- (B1)  $\blacktriangledown(p \wedge \neg q^0) \rightarrow p \vee \blacktriangledown(p \wedge q^1) \vee \blacktriangledown(p \wedge q^2)$ ,
- (B2)  $\blacktriangledown(p \wedge \neg q^1) \rightarrow p \vee \blacktriangledown(p \wedge q^0) \vee \blacktriangledown(p \wedge q^2)$ ,

$$(B3) \quad \nabla(p \wedge \neg q^2) \rightarrow p \vee \nabla(p \wedge q^0) \vee \nabla(p \wedge q^1),$$

$$(E) \quad p \rightarrow \blacktriangle(p \vee q^0 \vee q^1 \vee q^2).$$

**Proposition 7.** (A3), (A4), (B1), (B2), (B3) and (E) are in  $L_{euc}^\blacktriangle$ .

For all  $n \geq 0$  and for all  $\alpha : i \in \{1, \dots, n\} \mapsto \alpha(i) \in \{0, 1, 2\}$ , let us consider the following formula:

$$(C_n^\alpha) \quad \bigwedge \{p_i \wedge \nabla(\neg p_i \wedge \neg q_i^{\alpha(i)}) : 1 \leq i \leq n\} \rightarrow \bigwedge \{\nabla(\neg p_i \wedge \bigwedge \{\neg q_j^{\alpha(j)} : 1 \leq j \leq n\}) : 1 \leq i \leq n\}.$$

**Proposition 8.** For all  $n \geq 0$  and for all  $\alpha : i \in \{1, \dots, n\} \mapsto \alpha(i) \in \{0, 1, 2\}$ ,  $(C_n^\alpha)$  is in  $L_{euc}^\blacktriangle$ .

## 4 Completeness

Our proof of the completeness of  $L_{euc}^\blacktriangle$  is based on maximal consistent sets of formulas where ‘‘consistency’’ means ‘‘ $L_{euc}^\blacktriangle$ -consistency’’. If  $\Gamma$  is a set of formulas then let  $\square\Gamma = \{\varphi : \varphi \wedge \blacktriangle\varphi \in \Gamma\}$ . Let  $\Gamma_0$  be a maximal consistent set of formulas. We consider the following two cases: **(i)** for all  $\varphi \in FOR$ ,  $\blacktriangle\varphi \in \Gamma_0$ , **(ii)** there exists  $\varphi \in FOR$  such that  $\nabla\varphi \in \Gamma_0$ . In the former case, let  $A = \{(\Gamma_0, 0)\}$ ,  $B = \emptyset$  and  $C = \emptyset$ . Let  $\mathcal{M} = (W_{B,C}^A, R_{B,C}^A, V)$  be the model based on  $\mathcal{F}_{B,C}^A$  where  $V$  is the valuation on  $W_{B,C}^A$  such that for all atoms  $p$ ,  $(\Gamma_0, 0) \in V(p)$  iff  $p \in \Gamma_0$ .

**Proposition 9 (Former case: Truth Lemma).** For all  $\varphi \in FOR$ ,  $\mathcal{M}, (\Gamma_0, 0) \models \varphi$  iff  $\varphi \in \Gamma_0$ .

*Proof.* By induction on  $\varphi \in FOR$ . We only treat the case  $\blacktriangle\varphi$ . As mentioned, in this case  $\blacktriangle\varphi \in \Gamma_0$ . Moreover, it is easy to show that  $R_{B,C}^A = \emptyset$ , from which and the semantics of  $\blacktriangle$ , it follows immediately that  $\mathcal{M}, (\Gamma_0, 0) \models \blacktriangle\varphi$ .

In the latter case, let  $(\varphi_1, \varphi_2, \dots)$  be an enumeration, possibly with repetitions, of the set of all  $\varphi \in FOR$  such that  $\varphi \wedge \nabla\varphi \in \Gamma_0$ . For all  $i \geq 1$ , let  $\Delta_i = \square\Gamma_0 \cup \{\neg\varphi_i\}$ . Let  $(\psi_1, \psi_2, \dots)$  be an enumeration, possibly with repetitions, of  $FOR$ . Let  $(a_1, a_2, \dots) \in \{0, 1, 2\}^\omega$  be such that for all  $n \geq 0$  and for all  $i \geq 1$ ,  $\Delta_i \cup \{\psi_1^{a_1} \wedge \dots \wedge \psi_n^{a_n}\}$  is consistent. For all  $i \geq 1$ , let  $\Delta'_i$  be a maximal consistent set of formulas such that for all  $n \geq 0$ ,  $\Delta_i \cup \{\psi_1^{a_1} \wedge \dots \wedge \psi_n^{a_n}\} \subseteq \Delta'_i$ . Let  $\Delta' = \Delta'_1 \cup \Delta'_2 \cup \dots$ . Let  $(\chi_1, \chi_2, \dots)$  be an enumeration, possibly with repetitions, of the set of all  $\chi \in FOR$  such that  $\chi \wedge \nabla\chi \in \Delta'$ . For all  $i \geq 1$ , let  $A'_i$  be a maximal consistent set of formulas such that  $\square\Delta' \cup \{\neg\chi_i\} \subseteq A'_i$ . Let  $A = \{(\Gamma_0, 0)\}$ ,  $B = \{(\Delta'_i, 1) : i \geq 1\}$  and  $C = \{(A'_i, 2) : i \geq 1\}$ . Let  $\mathcal{M} = (W_{B,C}^A, R_{B,C}^A, V)$  be the model based on  $\mathcal{F}_{B,C}^A$  where  $V$  is the valuation on  $W_{B,C}^A$  such that for all atoms  $p$ ,  $(\Gamma_0, 0) \in V(p)$  iff  $p \in \Gamma_0$  and for all  $i \geq 1$ ,  $(\Delta'_i, 1) \in V(p)$  iff  $p \in \Delta'_i$  and  $(A'_i, 2) \in V(p)$  iff  $p \in A'_i$ .

**Proposition 10 (Latter case: Truth Lemma).** For all  $\varphi \in FOR$ ,  $\mathcal{M}, (\Gamma_0, 0) \models \varphi$  iff  $\varphi \in \Gamma_0$  and for all  $i \geq 1$ ,  $\mathcal{M}, (\Delta'_i, 1) \models \varphi$  iff  $\varphi \in \Delta'_i$  and  $\mathcal{M}, (A'_i, 2) \models \varphi$  iff  $\varphi \in A'_i$ .

Propositions 9 and 10 immediately yield the following result:

**Proposition 11 (Completeness).** For all  $\varphi \in FOR$ , if  $\varphi \in \text{Log}(\mathcal{C}_{euc})$  then  $\varphi \in L_{euc}^\blacktriangle$ .

## Acknowledgement

Jie Fan is funded by the grant number 2017T100050 of the China Postdoctoral Science Foundation.

## References

1. M. Cresswell. Necessity and contingency. *Studia Logica*, 47:145–149, 1988.
2. S. Demri. A completeness proof for a logic with an alternative necessity operator. *Studia Logica*, 58(1):99–112, 1997.
3. J. Fan. Strong non-contingency: on the modal logics of an operator expressively weaker than necessity. To appear in *Notre Dame Journal of Formal Logic*.
4. J. Fan, Y. Wang, and H. van Ditmarsch. Almost necessary. In *Advances in Modal Logic*, volume 10, pages 178–196, 2014.
5. J. Fan, Y. Wang, and H. van Ditmarsch. Contingency and knowing whether. *The Review of Symbolic Logic*, 8(1):75–107, 2015.
6. J. Hintikka. The semantics of questions and the questions of semantics: Case studies in the interrelations of logic, syntax, and semantics. *Acta Philosophica Fennica*, 28(4), 1976.
7. L. Humberstone. The logic of non-contingency. *Notre Dame Journal of Formal Logic*, 36(2):214–229, 1995.
8. S. Kuhn. Minimal non-contingency logic. *Notre Dame Journal of Formal Logic*, 36(2):230–234, 1995.
9. J. Marcos. Logics of essence and accident. *Bulletin of the Section of Logic*, 34(1):43–56, 2005.
10. H. Montgomery and R. Routley. Contingency and non-contingency bases for normal modal logics. *Logique et Analyse*, 9:318–328, 1966.
11. C. Steinsvold. Completeness for various logics of essence and accident. *Bulletin of the Section of Logic*, 37(2):93–101, 2008.
12. C. Steinsvold. Being wrong: Logics for false belief. *Notre Dame Journal of Formal Logic*, 52(3):245–253, 2011.